



The DS-70 is a member of the DS series of Electric Encoders<sup>™</sup>, based on Netzer Precision proprietary technology. The Electric Encoder<sup>™</sup> offers many advantages - some unparalleled

- Low profile (10 mm)
- Hollow, floating shaft.
- No bearings or other contacting elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Analog or Digital interfaces

#### General

Angular resolution	19 bits ; 524,288 CPR
Maximum tested static error	≤ 0.010°
Maximum operational speed	750 rpm
Measurement range	Unlimited rotation
Power On - Max. operational speed	3.3 RPM, <=20°/sec
Build In Test BIT	Optional

### Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	1,940 gr · mm²
Total weight	35 gr
Outer Ø /Inner Ø/ Height	70 / 30 / 10 mm
Material (stator, rotor)	Ultem <sup>™</sup> polymer

The Electric Encoder<sup>TM</sup> is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder<sup>TM</sup> forgiving to mounting tolerances, mechanical wander etc.

The absence of components such as ball bearings , flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder<sup>TM</sup> virtually failure free.

The internally shielded, DC operated Electric Encoder<sup>™</sup> includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder<sup>™</sup> are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.

#### Electrical

Supply voltage	5V ± 5%	
Interconnection	Shielded cable or	
Cable Length	1,500 mm MAX	

### Environmental

IEC 6100-6-2, IEC 6100-6-4
Digital: -40°C to +85°C
98% Non condensing
100 g for 11 ms
20 g 10 – 2000 Hz
IP 40











## Digital SSi Interface

Synchronous Serial Interface (SSI) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 22
Т	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	



## SSi / BiSS Output signal parameters

Signal latency	~250 µSec
Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.5 ÷ 2.0 MHz
Position update rate (Max)	30 KHz
Current consumption	180 mA
SSi	
Monoflop time	25 µSec

## SSi / BiSS interface wires color code

Clock +	Grey	Clock
Clock -	Blue	CIUCK
Data -	Yellow	Data
Data +	Green	Dala
GND	Black	Ground
+5V	Red	Power supply

## Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



HARSH

**ENVIRONMENT** 

## Digital BiSS-C Interface

**BiSS** – **C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

DS-70

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bit #		Description	Default	Length
29	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
28	Start	Encoder signal for "start" data transmit	1	1 bit
27	"0"	"start" bit follower	0	1 bit
826	AP	Absolute Position encoder data		
7	Error	Error (amplitude levels)	1	1 bit
б	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$ . It is transmitted MSB first and inverted.		6 bits
		The start bit and "0" bit are omitted from the		
		CRC calculation.		
	Time- out	Elapse between the sequential "start"request cycle's.		25 µs

DATA SHEET





Pair#

1

2

З

0.051 ± 0.051mm

Color

Red / Black

Gray / Blue

Green / Yellow

30 AWG single

insulated wire

## Ordering Code

## **Cable Information**



#### Related documents

DS-70 User Manual: Mechanical, Electrical and calibration setup.

## **Optional Accessories**

### Demonstration Kit DS-70DKIT-01: Includes ,mounted encoder on rotary jig, and RS-422 to USB converter.















#### WARNING



Do not use Loctite or other glues containing Cyanoacrylate. We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhesive EC-2216 B/A.

#### Notes:

 For any incompatibility with the model or missing dimension, please refer to Netzer for clarification.
All installation dimensions and tolerances are according to DS-70 ICD drawing.
All dimensions marked with \* are critical for encoder installation.

No	Part			Description	QTY.
1	DS-70-64-3SH	Included		DS-70 encoder	1
2			Shaft End	MP-03085-00 spring	1
3	— MA-DS70-004	Optional	l installation kit	MP-00329 DIN 912 M2 X 4 Alen	1
4		Optional		Star washer DIN 6798A M2	3
5	EAPK008	Optional	Mounting Kit	DIN 912 M2 X 6mm Alen	3

Critical dimensions marked with "\*"