



The DS-58 is a member of the DS series of Electric Encoders™ a product line based on Netzer Precision Motion Sensor proprietary technology. EE products are characterized by features that enable unparalleled performance:

featuresLow profile (10 mm)

- Hollow, floating shaft
- No bearings or other contact elements
- High resolution and unparalleled precision
- High tolerance to temperature extremes, shock, EMI, RFI and magnetic fields
- Very low weight
- Holistic signal generation
- Digital interfaces for absolute position

General

Angular resolution ¹	18 bits ; 262,144 CPR
Maximum tested static error ²	≤ 0.010°
Maximum operational speed	4,000 rpm
Measurement range	Single turn, unlimited

Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	684 gr · mm²
Total weight	36 gr
Outer Ø /Inner Ø/ Height	58 / 20 / 10 mm
Material (stator, rotor)	Ultem™ polymer

Notes - Optional (Call)

1	Angular resolution	19 - 20 bit
2	Static error	≤ 0.008°
3	Operating temperature	-40 °C to +125 °C

The holistic structure of the Electric EncoderTM makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.

Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.

The internally shielded, DC - operated EE includes an electric field generator, a field receiver, sinusoidal-shaped dielectric rotor, and processing electronics.

The EE output is a digital serial synchronous with absolute position single turn.

This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation and harsh environment applications.

Electrical

Supply voltage	5V ± 5%
Current consumption	≤ 70 mA
Interconnection	Shielded cable

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4	
Operating temperature ³	-40°C to +85°C	
Storage temperature	-60°C to +125°C	
Relative humidity	98% Non condensing	
Shock endurance	100 g for 11 ms	
Vibration endurance	20 g 10 – 2000 Hz	
Protection	IP 40	











Digital SSi Interface

Synchronous Serial Interface **(SSi)** is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations	
n	Total number of data bits	12 - 22	
Т	Clock period		
f= 1/T	I/T Clock frequency 0.1 - 5.0 MHz		
Tu	Bit update time	90 nsec	
Тр	Pause time	26 - ∞ µsec	
Tm	Monoflop time >25 µsec		
Tr	Time between 2 adjacent requests $Tr > n^{*}T+26 \mu second$		
fr=1/Tr	Data request frequency		



SSi / BiSS output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.1 ÷ 5.0 MHz
Position update rate	35 kHz (Optional - up to 375 KHz)

SSi / BiSS interface wires color code

Clock +	Grey	Clock
Clock -	Blue	CLOCK
Data -	Yellow	Data
Data +	Green	
GND	Black	Ground
+5V	Red	Power supply

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.





HARSH

ENVIRONMENT

Digital BiSS-C Interface

DATA SHEET

BiSS – **C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

DS-58 @core

Master Clock



Bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"0"	"start" bit follower	0	1 bit
825	AP	Absolute Position encoder data		
7	Error	Error (BIT optional)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 µs

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Ordering Code



Cable Information

Netzer Cat No.: CB 00014 Cable: 30 AWG twisted pair (3): 2 (30 AWG 25/44 tinned copper, Insulation: PFE Ø 0.15 to Ø 0.6 ± 0.05 OD) Temperature rating: -60 to +150 Deg C Braided shield: Thinned copper braided 95% min. coverage Jacket: 0.44 silicon rubber (NFA 11-A1) Ø3.45 ±0.2 OD





Related documents DS-58 User Manual : Mechanical , Electrical and calibration setup.

Optional Accessories

Demonstration Kit

DKIT-DS-58-SG with SSi interface DKIT-DS-58-IG with BiSS interface Includes, mounted encoder on rotary jig, and RS-422 to USB converter.





ICD



SECTION A-A





DATA SHEET

Shaft - End installation (step)

UNLESS OTHERWISE SPECIFIED

Dimentions are in: mm

Linear Tolerances: ±0.5 deg

All Chamfer: 0.1 mm x 45°

Surface Finish: N6





Description No Part QTY. DS-58 1 DS-58 encoder 1 Included Kit, 3 x M2 Encoder 2 EAPK005 Included Kit clamps ST. ST. 3 End shaft spring 1 Shaft End MA-DS58-004 Optional installation Screw DIN 912 4 3 kit M2x4

Critical dimensions marked with "*"

WARNING

2.50 min

Do not use Loctite or other glues containing Cyanoacrylate. We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhesive EC-2216 B/A.

Ø7.30 TYP3



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MA-DS58-004 End of shaft spring



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DATA SHEET

Shaft - MID installation (step)



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